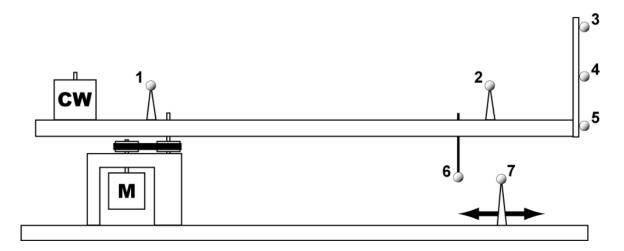
# GCMAS Standard Assessment for Motion System Accuracy (SAMSA)

#### **Device Plans**

#### **Notes:**

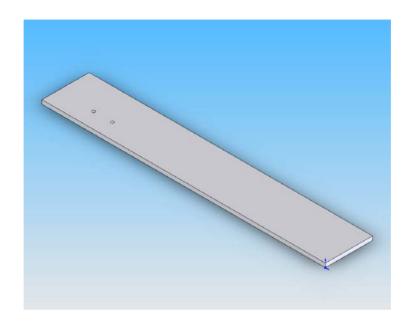
- 1. All dimensions are given in centimeters.
- 2. The motor housing and transmission may vary; any arrangement that produces 60 rpm rotation of the beam with respect to the base is acceptable. Parts used in the prototype are listed on the next page.
- 3. The mass and placement of your counterweight should be selected such that the beam is balanced about the point where the shaft attaches.
- 4. Aluminum was used for the prototype, with "80/20" extruded aluminum (http://industrialerectorset.com/) used for the beam.
- 5. Markers 0.5 in (12.7 mm) diameter were used with the prototype; you should use the same size markers that you test with in your laboratory.

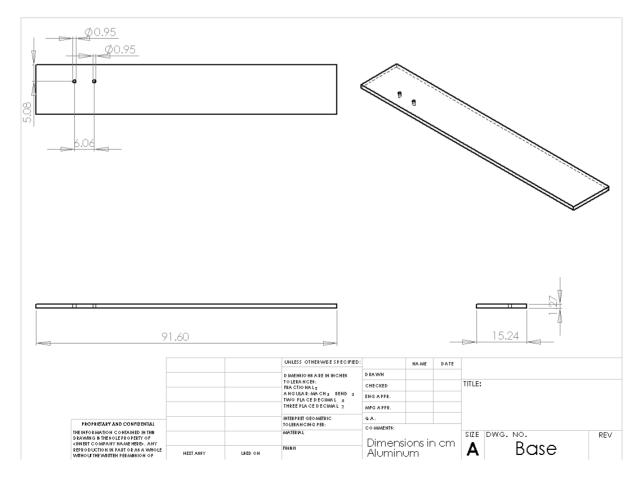


#### **Motor and Transmission Parts List:**

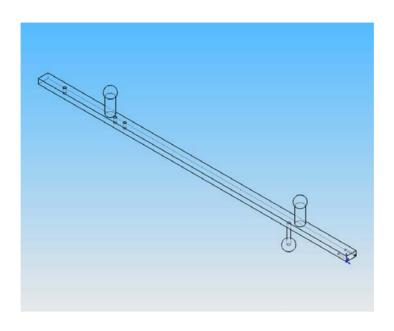
- Gearmotor
   Hurst Manufacturing (PB3204-024) 60 RPM, 115 VAC, Full Load
   Torque 2.6 In-Lbs; available from Grainger Industrial Supply (6A179)
- 2. Ball Bearings (2)
  Double-sealed, 0.5 in shaft dia; available from McMaster-Carr (60355K36)
- 3. Gearbelt Pulleys (2)
  Browning (15XLB037); available from Grainger Industrial Supply (2L518)
- 4. Gearbelt
  Browning (80XL037); available from Grainger Industrial Supply (2L558)

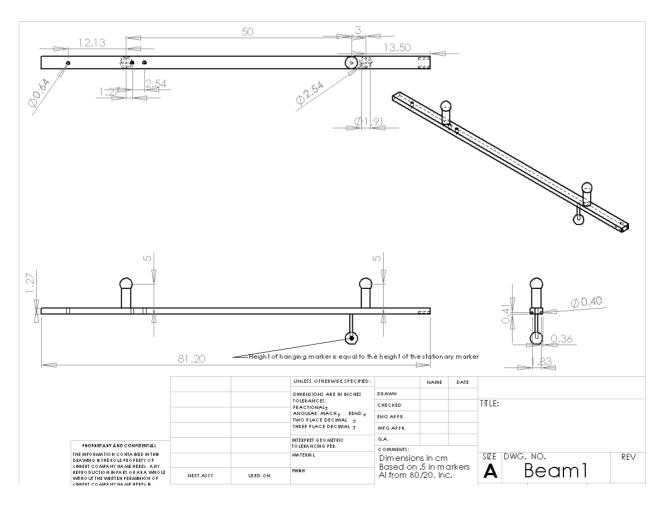
### Base



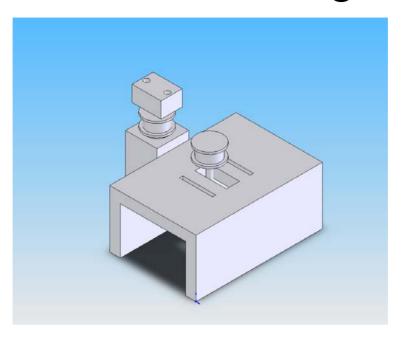


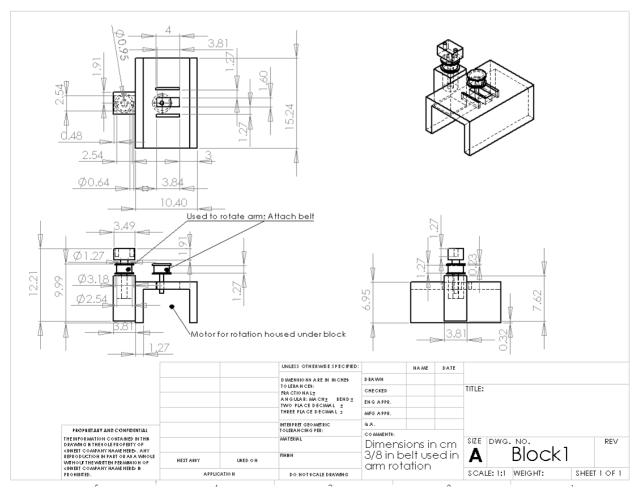
### Beam



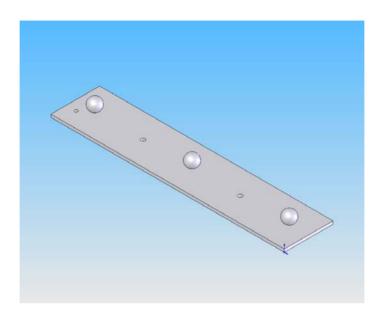


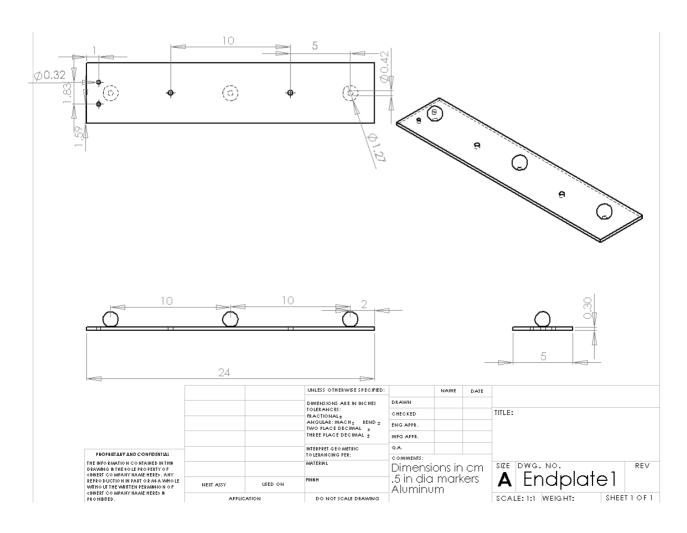
## **Motor Housing**





### **Plate**





# **Stationary Marker Mount**

